M

180° ANGULAR GRIPPER - Rack & pinion style



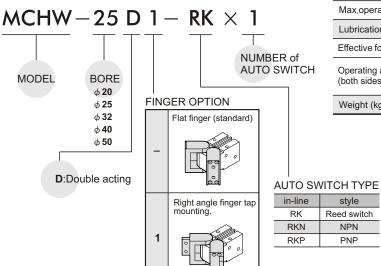


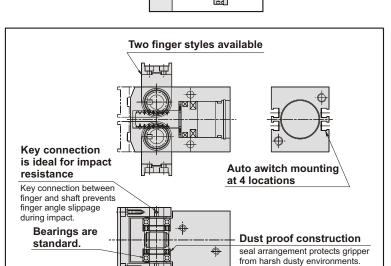
Features:

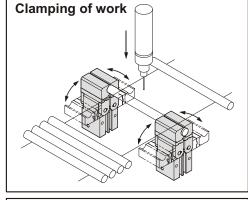
- For applications where saving space is a necessity.
- Each one of the two fingers, synchronized by a rack and pinion, rotates back perpendicular to the gripper.
- Dust proof construction.
- Auto switch mounting at 4 locations.

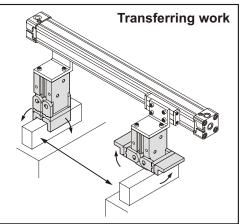
Specification:

Mod	lel	MCHW							
Acting Type		Double Acting							
Tube I.D. (mm)		20	25	32	40	50			
Medium			•	Air	•				
Operating pressure	e range		1.5	~7 kgf/	cm²				
Ambient tempera	ture	-10~+60°C (No freezing)							
Repeatability (mn	n)	±0.2							
Max.operating fre	quency(c.p.m)	60	60 30						
Lubrication		Not required							
Effective force (Nr	n) at (5kgf/cm²)	0.30	0.73	1.61	3.70	8.27			
Operating angle	Opened side			180°					
(both sides)	Closed side	-5°	-6°	-5°	-5°	-4°			
Weight (kg)	Weight (kg)				2.2	5.15			





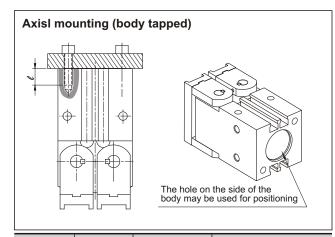






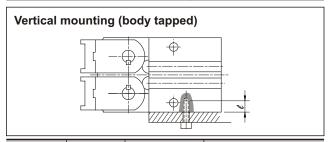
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Mounting



Model	Bolt	Max.torque N.m	Max.screw depth ℓ (mm)
MCHW-20	M5×0.8	4.3	10
MCHW-25	M6×1	7.4	12
MCHW-32	M6×1	7.4	12
MCHW-40	M8×1.25	17.7	15
MCHW-50	M10×1.5	37.2	20

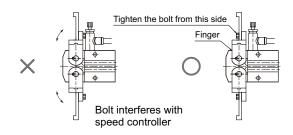
Model	Hole diameter (mm)	Height (mm)
MCHW-20	φ 21H9 +0.052	3
MCHW-25	φ 26H9 +0.052	3
MCHW-32	φ 34H9 +0.062	4
MCHW-40	φ 43H9 +0.062	4
MCHW-50	φ 52H9 +0.074	5

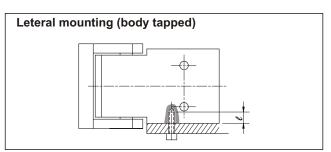


Model	Bolt	Max.torque N.m	Max.screw depth ℓ (mm)
MCHW-20	M5×0.8	2.9	7
MCHW-25	M6×1	5.9	10
MCHW-32	M6×1	5.9	10
MCHW-40	M8×1.25	17.7	15
MCHW-50	M10×1.5	37.2	20

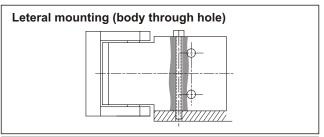
Warning

• When using right angle finger tap mounting type, pay attention the interference of bolt and speed controller.



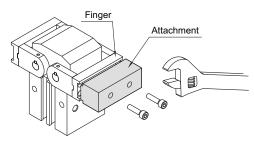


Model	Bolt	Max.torque N.m	Max.screw depth ℓ (mm)
MCHW-20	M5×0.8	4.3	10
MCHW-25	M6×1	7.4	12
MCHW-32	M6×1	7.4	12
MCHW-40	M8×1.25	17.7	16
MCHW-50	M10×1.5	37.2	20



Model	Bolt	Max.torque N.m
MCHW-20	M4×0.7	2.1
MCHW-25	M5×0.8	4.3
MCHW-32	M5×0.8	4.3
MCHW-40	M6×1	7.4
MCHW-50	M8×1.25	17.7

How to mount attachment on fingers



- To mount an attachment to a finger, make sure to use a wrench to support the attachment so as not to apply undue strain on the finger.
- Refer to the table below for the proper tightening torque on the bolt used for securing the attachment to the finger.

Model	Bolt	Max.torque N.m
MCHW-20	M4×0.7	1.4
MCHW-25	M5×0.8	2.5
MCHW-32	M6×1	4.1
MCHW-40	M8×1.25	10.6
MCHW-50	M10×1.5	24.5



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Effective holding force

Indication of effective holding force

- 1.Although the condition differs according to the coefficient of friction between the attachment and work, select a model that can produce a holding force of 10 to 20 times the work.
- Further allowance should be provided when great acceleration or impact is expected during work transfer.

Ex.

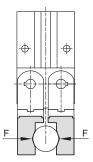
For setting the holding force to be at least 20 times the work weight;

Required holding force = 0.1kg X 20 X 9.8m/s² = 20N min.

When MCHW-25 is selected, the holding force is determined to be 23N according to the holding point distance (L = 30mm) and the pressure (5kgf/cm²).

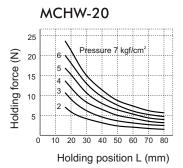
3.The holding force shown in the tables represents the holding force of one finger when all fingers and attachments are in contact with the work.

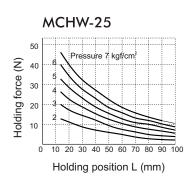
L: Holding point distance

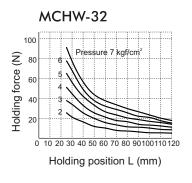


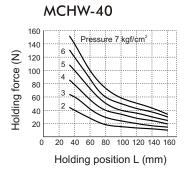
F: Thrust of one finger

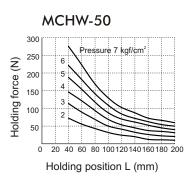
External hold





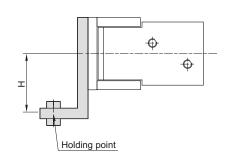


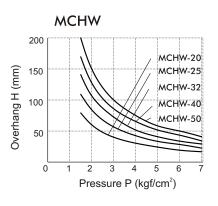




Confirmation of holding point

Work should be held at a point within the tange of overhanging distance (H) for a given preaaure bindicated in the tables. When the work is held at a point outside of the recommended range for a given pressure. it may causes adverse effect on the product life.



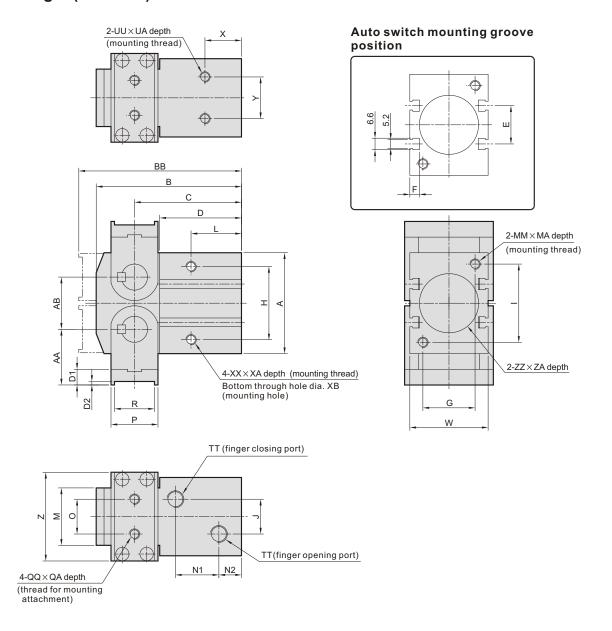


MCHW Dimensions $\phi 20 \sim \phi 50$



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Flat finger (standard)



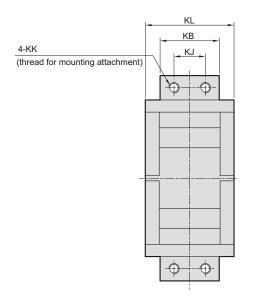
Code Tube I.D.	Α	AA	AB	В	BB	С	D	D1	D2	Е	F	G	Н	Ι	J	L	M	MA	MM	N1	N2	0	Р
20	36	23	18	60	68	45	35	7	2	8	5	26	27	26	12	23	30	10	M5×0.8	20	9	18	16
25	45	27	24	69	78	51	40	8	2	9	5	30	34	30	16	27	30.3	12	M6×1	23	10	20	21
32	58	32	30	83.5	93.5	61.5	47	9	2	22	5.5	30	42	45	20	29	32.9	12	M6×1	25	13	20	27
40	80	42	40	104.5	117.5	75.5	56.5	12	3	20	5	36	54	60	20	37.5	45	15	M8×1.25	33.5	14	28	36
50	112	58	56	136	154	96	69	17	4	26	5	40	70	80	30	48	58.6	20	M10×1.5	22	16	38	52

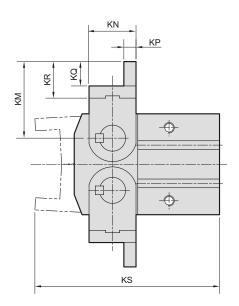
Code Tube I.D.	R	QA	QQ	TT	UA	UU	W	Х	XA	ХВ	XX	Υ	Z	ZA	ZZ
20	12 +0.2	5	M4×0.7	M5×0.8	7	M5×0.8	36	17	10	4.2	$M5 \times 0.8$	20	41	3	φ 21H9 ^{+0,052} ₊₀
25	17 +0.2	6	M5×0.8	M5×0.8	10	M6×1	40	20	12	5.1	M6×1	24	45	3	φ 26H9 ^{+0,052}
32	23 +0.2	7	M6×1	Rc 1/8	10	M6×1	45	21	12	5.1	M6×1	24	51	4	φ 34H9 ^{+0,062}
40	30 +0.3	9	M8×1.25	Rc 1/8	16	M8×1.25	56	27.5	16	6.8	M8×1.25	30	67	4	φ 42H9 ^{+0,062} ₊₀
50	44 +0.4	13	M10×1.5	Rc 1/4	20	M10×1.5	66	36	20	8.5	M10×1.5	40	85	5	φ 52H9 ^{+0,074} ₊₀



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Right angle finger





	Code Tube I.D.	KA	KB	KJ	KK	KL	KM	KN	KP	KQ	KR	KS
	20	5	28	14	M4×0.7	41	31	16	5	10	15	76
	25	6	30	16	M5×0.8	45	37	21	6	12	18	88.5
·	32	7	34	18	M6×1	51	44	27	7	14	21	106
	40	10	44	24	M8×1.25	67	60	36	10	21	30	136
	50	12	58	30	M10×1.5	85	85	52	13	24	37	175